# Lecture 5

## The modular curves *X*(Γ)

In Lecture 3, we saw that the set of isomorphism classes of elliptic curves *E*C were in bijection with classes of homothetic lattices  $\Lambda \subset \mathbb{C}$ , which were in turn in bijection with elements of  $Y(1)$  =  $SL_2(\mathbb{Z})\backslash\mathcal{H}$ . In Lecture 4, we then saw that  $X(1)$  is a compact Riemann surface.

Recall that given a lattice Λ, we define the *j*-invariant of Λ

$$
j(\Lambda) = 1728 \frac{g_2(\Lambda)^3}{g_2(\Lambda)^3 - 27g_3(\Lambda)^2},
$$

where  $g_2$  and  $g_3$  are defined in terms of the Eisenstein series of weights 4 and 6, respectively. Homothetic lattices  $\Lambda$  and  $\Lambda'$  have  $j(\Lambda) = j(\Lambda')$ , and every lattice  $\Lambda$  is homothetic to a lattice  $\Lambda_{\tau} = \tau \mathbb{Z} + \mathbb{Z}$ , where  $\tau \in \mathcal{H}$ . We then define the function  $j : \mathcal{H} \to \mathbb{C}$ ,  $j(\tau) = j(\Lambda_{\tau})$ . This function is holomorphic on H and satisfies  $j(S\tau) = j(\tau)$  and  $j(T\tau) = j(\tau)$  for the matrices

$$
S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \text{ and } T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix},
$$

which generate  $SL_2(\mathbb{Z})$ ; thus we have a well-defined map  $j : Y(1) \to \mathbb{C}$ . This map is surjective, and by defining  $j(\infty) = \infty$ , we have a meromorphic function  $j : X(1) \to \mathbb{P}^1(\mathbb{C})$  which is, in fact, an isomorphism of Riemann Surfaces. The modular curve  $X(1)$ , can therefore, be identified with the Riemann sphere *S* 2 .

More generally, for a congruence subgroup  $\Gamma \subseteq SL_2(\mathbb{Z})$ , we may again define the quotient space *Y*(Γ). This space is not compact, but by adjoining finitely many cusps (corresponding to the orbits of  $\mathbb{Q} \cup \{\infty\}$  under the action of Γ), we obtain the modular curves  $X(\Gamma)$  which is again a compact Riemann surface. Each *X*(Γ) is, topologically, a sphere with *g* handles. This nonnegative integer *g* is the genus of the surface. The Riemann sphere has 0 handles, thus its genus is 0. The genus of a curve is not only a topological invariant, it has "arithmetic" signifcance as well: for example, by Faltings's Theorem, a curve of genus *g >* 1 can have only finitely many Q-rational points (or more generally only finitely many  $K$ -rational points for any finite degree extension of  $\mathbb{Q}$ ). We will see some of the implications of this in the next lecture. For now, we discuss how to determine the genus *g* of a modular curve *X*(Γ).

## The genus of *X*(Γ)

If  $f: X \to Y$  is a holomorphic map between Riemann surfaces, then f is surjective and there is a fixed positive integer *d* (the degree of the map) such that for all but finitely many  $y \in Y$ .  $|f^{-1}(y)| = d$  so that the map f is d-to-1. In other words, for most  $x \in X$ , the multiplicity of *x* is  $e_x = 1$ , so that *f* is 1-1 about *x*. This integer  $e_x$  is known as the ramification index of *x*. There are sometimes points  $x \in X$  for which  $e_x > 1$ ; these points are said to be ramified. The Riemann-Hurwitz formula gives us a way to relate the genus  $g_X$  of X to the genus  $g_Y$  of Y.

**Theorem 1 (Riemann-Hurwitz Formula)** *Let X and Y be compact Riemann surfaces, and let*  $f: X \to Y$  *be a nonconstant holomorphic map of degree d. Then* 

$$
2g_X - 2 = d(2g_Y - 2) + \sum_{x \in X} (e_x - 1).
$$

As  $X(1)$  is of genus 0, for a congruence subgroup  $\Gamma$  we can use the natural map

$$
f: X(\Gamma) \to X(1),
$$

$$
\Gamma \tau \mapsto \mathrm{SL}_2(\mathbb{Z})\tau
$$

to determine the genus of *X*(Γ).

**Theorem 2** *Let*  $\Gamma_1 \subseteq \Gamma_2$  *be congruence subgroups. Then the map* 

*has degree*

$$
m = \begin{cases} [\Gamma_2 : \Gamma_1]/2 & \text{if } -I_2 \in \Gamma_2 \setminus \Gamma_1 \\ [\Gamma_2 : \Gamma_1] & \text{otherwise} \end{cases}
$$

For example, since  $-I_2 \in \Gamma(2)$  and  $|SL_2(\mathbb{Z}/2\mathbb{Z})| = 6$ , the map  $X(2) \to X(1)$  is of degree 6.

We saw in the last lecture that for each  $x \in X(1)$  corresponding to  $\tau \in \mathcal{F}^*$  (a fundamental domain for the action on  $\mathcal{H}^*$ ), there is some neighborhood  $U_x$  of  $\tau_x$  such that  $\gamma U_x \cap U_x = \emptyset$  for all  $\gamma \neq \tau_x$ . From this, we obtain an open cover  $\{\pi(U_x)\}\$  of  $X(1)$  along with maps  $\psi_x : \pi(U_x) \to \mathbb{D}$ which give a complex structure on *X*(1). For most  $x \in X(1)$ , the projection map  $\pi : \mathcal{H}^* \to X(1)$ restricted to  $U_x$  is a homeomorphism, but for  $x \in \{i, e^{\frac{\pi i}{3}}, \infty\}$  the map is not injective. To correct for this, we had to define the homeomorphisms  $\psi_x$  in a slightly different fashion for these points than for the other points of  $X(1)$ . A similar issue arises for  $X(\Gamma)$ . In a fundamental domain  $F_{\Gamma}$  for Γ, the set {±*I*2}*Stab*Γ*<sup>τ</sup>* = {±*I*2}{*γ* ∈ Γ : *γτ* = *τ*} will consist only of {±*I*2}, and on an appropriate neighhborhood of  $\tau$ , the restriction of the quotient map  $\mathcal{H}^* \to X(\Gamma)$  will be a homeomorphism. The possible exceptions are those  $\tau$  in the orbit of *i*,  $e^{\pi i/3}$ , or  $\infty$ .

**Definition 3** Let  $\Gamma$  be a subgroup of  $SL_2(\mathbb{Z})$ . A point  $\tau \in \mathcal{H}$  is an elliptic point for  $\Gamma$  if  ${\{\pm I_2\}} \subset {\{\pm I_2\}}$ *Stab<sub>* $\tau$ *</sub> . We say*  $x = \Gamma \tau \in X(\Gamma)$  *is elliptic if*  $\tau$  *is an elliptic point.* 

**Example 4** *The elliptic points for*  $SL_2(\mathbb{Z})$  *are <i>i* and  $-\bar{\omega} = e^{\pi i/3}$ .

**Definition 5** *If*  $\Gamma \tau \in X(\Gamma)$  *is an elliptic point, its period is* 

$$
|\{\pm I_2\}Stab_{\Gamma_{\tau}}:\{\pm I_2\}| = \begin{cases} |Stab_{\Gamma_{\tau}}|/2 & \text{if } -I_2 \in \Gamma \\ |Stab_{\Gamma_{\tau}}| & \text{otherwise} \end{cases}
$$

Now, two points of  $\mathcal{H}^*$  may be in different  $\Gamma$  orbits despite being in the same  $SL_2(\mathbb{Z})$  orbit. By keeping track of elliptic points of  $\Gamma$  and determining their ramification indices, we can compute the genus of  $X(\Gamma)$ .

**Theorem 6** *Let*  $\Gamma \subseteq SL_2(\mathbb{Z})$  *be a congruence subgroup of*  $SL_2(\mathbb{Z})$  *and let m be the degree of the natural map*  $X(\Gamma) \to X(1)$ *. Let*  $\epsilon_2$  *denote the number of elliptic points of period 2,*  $\epsilon_3$  *the number of elliptic points of period 3, and*  $\epsilon_{\infty}$  *the number of cusps of*  $\Gamma$  *(i.e., the number of orbits of*  $\Gamma$  *on*  $\mathbb{Q} \cup \{\infty\}$ *. Then then genus of*  $X(\Gamma)$  *is* 

$$
g(X(\Gamma)) = 1 + \frac{m}{12} - \frac{\epsilon_2}{4} - \frac{\epsilon_3}{3} - \frac{\epsilon_{\infty}}{2}
$$

For a proof, see [\[2,](#page-4-0) Thm. 2.22].

**Example 7**  $X(2)$  has no elliptic points of order 2 or 3 and has 3 cusps. Thus  $g(X(2)) = 0$ .

### Points on *Y* (Γ)

Just as the points of *Y* (1) parametrize elliptic curves, the points on the other modular curves we are most interested parameterize elliptic curves, but this time with additional torsion data.

Recall, for a positive integer *N*, the principal subgroup of level *N*, denoted Γ(*N*) is

$$
\Gamma(N) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbb{Z}) : \begin{pmatrix} a & b \\ c & d \end{pmatrix} \equiv \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \pmod{N} \right\},\
$$

where we reduce the entries of the matrix  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$  modulo *N*. A subgroup  $\Gamma \subseteq SL_2(\mathbb{Z})$  is a congruence subgroup if  $\Gamma(N) \subseteq \Gamma$  for some *N*. The two we will most focus on are

$$
\Gamma_1(N) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbb{Z}) : \begin{pmatrix} a & b \\ c & d \end{pmatrix} \equiv \begin{pmatrix} 1 & * \\ 0 & 1 \end{pmatrix} \pmod{N} \right\},\
$$

(where the ∗ indicates that there are no conditions on *b* modulo *N*) and

$$
\Gamma_0(N) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbb{Z}) : \begin{pmatrix} a & b \\ c & d \end{pmatrix} \equiv \begin{pmatrix} * & * \\ 0 & * \end{pmatrix} \pmod{N} \right\},\
$$

To see how points of these curves parameterize elliptic curves with additional torsion data, first recall that if  $\phi : \mathbb{C}/\Lambda_1 \to \mathbb{C}/\Lambda_2$  is a holomorphic map, then there are  $m, b \in \mathbb{C}$  with  $m\Lambda_1 \subset \Lambda_2$ and  $\phi(z + \Lambda_1) = (mz + b) + \Lambda_2$ .

When  $\phi(0 + \Lambda_1) = 0 + \Lambda_2$ , this map is a group homomorphism.

**Definition 8** *A holomorphic group homomorphism of complex tori is called an isogeny.*

When  $\phi : \mathbb{C}/\Lambda_1 \to \mathbb{C}/\Lambda_2$  is not the zero map, it is nonconstant. Therefore,  $\phi$  is surjective. Moreover, the kernel, being a discrete subgroup of a compact space, is finite. To understand the kernel, we can use two kinds of isogenies. The first is the multiplication by *N* map. For  $N \in \mathbb{Z}^+$ , the map  $[N]$  is given by

$$
[N]:\mathbb{C}/\Lambda\to\mathbb{C}/\Lambda
$$

$$
z+\Lambda\mapsto Nz+\Lambda
$$

If  $\Lambda$  has an oriented basis  $\{\omega_1, \omega_2\}$ , then the kernel of this map consists of points *P* of the form

$$
P = \frac{c\omega_1 + d\omega_2}{N} + \Lambda
$$

Let  $E = \mathbb{C}/\Lambda$  be an elliptic curve. As an abstract group, the set of *N*-torsion points denoted  $E[N]$ (i.e., the kernel of  $[N]$  is isomorphic as an abstract group to  $\mathbb{Z}/N\mathbb{Z} \times \mathbb{Z}/N\mathbb{Z}$ .

In addition to the multiplication by *N* map, for a cyclic subgroup *C* of *E*[*N*], we obtain a map

$$
\mathbb{C}/\Lambda \to \mathbb{C}/C
$$

$$
z + \lambda \mapsto z + C
$$

so that *C* is the kernel of the isogeny. Again refering to an oriented basis  $\{\omega_1, \omega_2\}$ , a cyclic subgroup of order *N* can be given by the lattice generated by  $\omega_1$  and  $\omega_2/N$ . If, for example,  $\Lambda = \Lambda_{\tau}$ , then the cyclic subgroup *C* is  $\tau \mathbb{Z} + \frac{1}{N}$  $\frac{1}{N}\mathbb{Z}.$ 

We are nearly ready to state the correspondence between points on  $Y(N)$ ,  $Y_1(N)$  and  $Y_0(N)$ and isomorphism classes of "elliptic curves with certain torsion data." For identifying points of *Y* (*N*), we first need to define the Weil pairing. Note that we will be following Diamond and Shurman's definition  $([1, \S 1.3])$  $([1, \S 1.3])$  $([1, \S 1.3])$ , but it is possible to define the Weil pairing using, for example, divisors (see for example [\[3,](#page-4-2) §3.8]).

Given an elliptic curve *E* corresponding to a lattice  $\Lambda = \omega_1 \mathbb{Z} + \omega_2 \mathbb{Z}$  with  $\omega_1/\omega_2 \in \mathcal{H}$ , and given points  $P, Q$  in  $E[N]$  there is some matrix  $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_2(\mathbb{Z}/N\mathbb{Z})$  such that  $P = \frac{a\omega_1}{N} + \frac{b\omega_2}{N} + \Lambda$  and  $Q = \frac{c\omega_1}{N} + \frac{d\omega_2}{N} + \Lambda$ , we define  $e_N(P, Q)$  to be

$$
e_N(P,Q) = e^{2\pi i \det(\gamma)/N}
$$

. This pairing has

$$
e_N: E[N] \times E[N] \to \mu_N,
$$

where  $\mu_N$  denotes the *N*<sup>th</sup> roots of unity. We make the following claims:

#### **Theorem 9** *The Weil pairing is*

*(i) Bilinear:*

$$
e_N(P_1 + P_2, Q) = e_N(P_1, Q)e_N(P_2, Q)
$$

*and*

$$
e_N(P, Q_1 + Q + 2) = e_N(P, Q_1)e_N(P, Q_2)
$$

*(ii) Alternating:*

 $e_N(P, P) = 1$  *and in particular,*  $e_N(P, Q) = e_N(Q, P)^{-1}$ 

*(iii) Nondegenerate:*

If 
$$
e_N(P,Q) = 1
$$
 for all  $P \in E[N]$ , then  $Q = 0$ 

Having introduced the Weil pairing, we can describe points of  $Y(N)$ : A point of  $Y(N)$  corresponds to an isomorphism class of a triple  $[E, P, Q]$  where P and Q are a basis for  $E[N]$  and  $e_N(P, Q)$  $e^{2\pi i/N}$ . The triples  $[E, P, Q]$  and  $[E', P', Q']$  are equivalent if there is an isomorphism  $\phi : E \to E'$ such that  $\phi(P) = P'$  and  $\phi(Q) = Q'$ .

A point on  $Y_1(N)$  corresponds to a pair  $[E, P]$ , where P is a point of E of order N. Two such pairs  $[E, P]$  and  $[E', P']$  are equivalent if there is an isomorphism  $\phi : E \to E'$  such that  $\phi(P) = P'$ .

A point on *Y*0(*N*) corresponds to a pair [*E, C*] where *C* is a cyclic subgroup of *E* of order *N*. Two such pairs  $[E, C]$  and  $[E', C']$  are equivalent if there is an isomorphism  $\phi : E \to E'$  such that  $\phi(C) = C'$ .

We can identify an elliptic curve  $E$  with  $\mathbb{C}/\Lambda$ , but we can actually do more.

**Theorem 10** *Let N be a positive integer.*

*(i)* Each point  $[E, P, Q]$  of  $Y(N)$  is equivalent to  $[\mathbb{C}/\Lambda_{\tau}, \tau/N + \Lambda_{\tau}, 1/N + \Lambda_{\tau}]$  for some  $\tau \in \mathcal{H}$ . Two points  $[\mathbb{C}/\Lambda_{\tau}, \tau/N + \Lambda_{\tau}, 1/N + \Lambda_{\tau}] = [\mathbb{C}/\Lambda_{\tau}', \tau'/N + \Lambda_{\tau}', 1/N + \Lambda_{\tau}']$  if and only if  $\Gamma(N)\tau = \Gamma(N)\tau'$ 

*(ii)* Each point  $[E, P]$  of  $Y_1(N)$  is equivalent to  $[\mathbb{C}/\Lambda_{\tau}, 1/N + \Lambda_{\tau}]$  for some  $\tau \in \mathcal{H}$ . Two points  $[\mathbb{C}/\Lambda_{\tau}, 1/N + \Lambda_{\tau}]$  and  $[\mathbb{C}/\Lambda_{\tau}, 1/N + \Lambda_{\tau}]$  are equal if and only if  $\Gamma_1(N)\tau = \Gamma_1(N)\tau'$ 

*(iii)* Each point  $[E, C]$  of  $Y_0(N)$  is equivalent to  $[\mathbb{C}/\Lambda_{\tau}, \langle 1/N + \Lambda_{\tau} \rangle]$  for some  $\tau \in \mathcal{H}$ . Two *points*  $[\mathbb{C}/\Lambda_{\tau}, \langle 1/N + \Lambda_{\tau} \rangle]$  *and*  $[\mathbb{C}/\Lambda_{\tau}, \langle 1/N + \Lambda_{\tau}]$  *are equal if and only if*  $\Gamma_0(N)\tau = \Gamma_0(N)\tau'$ 

For a proof of part (ii), see  $[1, Thm. 1.5.1]$  $[1, Thm. 1.5.1]$ 

# References

- <span id="page-4-1"></span>[1] Diamond, F. and Shurman, J. *A First Course in Modular Forms.* Springer 2016, 4th. printing.
- <span id="page-4-0"></span>[2] Milne, J.S., *Modular Functions and Modular Forms*, [https://www.jmilne.org/math/](https://www.jmilne.org/math/CourseNotes/mf.html) [CourseNotes/mf.html](https://www.jmilne.org/math/CourseNotes/mf.html)
- <span id="page-4-2"></span>[3] Silverman, J. *The Arithmetic of Elliptic curves, second edition*, Springer 2009.