#### **Definitions and Notation:**

- $M \approx \mathbb{Z}^d$  is a lattice,  $N = \text{Hom}(M, \mathbb{Z})$ ,
- A pairing  $\langle *, * \rangle : M \times N \to \mathbb{Z}$ .
- A finite subset  $A = \{v_1, \ldots, v_m\} \subset M$ .
- The vector space  $M_{\mathbb{R}} = M \otimes \mathbb{R}$ .
- $\Delta = \operatorname{Conv}(A) \subset M_{\mathbb{R}}$  is the convex hull of A in  $M_{\mathbb{R}}$ .

- Special/Regular Case:  $\dim \Delta = d 1$  such that  $\exists u \in N$  with  $\langle u, v_i \rangle = 1$  for all i = 1, 2, ..., n.
- General case with  $\dim = d$  can be reduced to a regular case with  $\dim = d + 1$ :

$$M \to \tilde{M} = \mathbb{Z} \oplus M$$
 (1)

$$\tilde{N} = \mathbb{Z} \oplus N \tag{2}$$

(3)

And a new pairing:  $\langle \tilde{x}, \tilde{y} \rangle \to \mathbb{Z}$ .

• Take a polytope  $\Delta \subset M_{\mathbb{R}}$  to  $\tilde{\Delta} = \text{Conv}((1, \Delta))$ .

- Example: Take  $\Delta = [0, n] \cap \mathbb{Z}$  into the line y = 1 in  $\mathbb{R}^2$ .
- Reverse process: General case of dimension d to a regular of dimension d-1 by restriction.
- Main Idea: A Laurent polynomial  $f(x) = \sum_{m \in A} a_m x^m$  with  $a_m \in K$ , so  $f \in k[M] \approx k[x_1^{\pm 1}, \dots, x_n^{\pm n}]$ .
- Could take  $k = \mathbb{R}, \mathbb{C}, \mathbb{F}_p$ , etc.

- Consider affine space  $\mathbb{A}_k^{|A|} \subset \mathbb{A}_k^{\#(\Delta \cap M)}$ .
- $\Delta = \text{Conv}(A), A \subset (\Delta \cap M).$
- A contains all the vertices of  $\Delta$ .

### Non-Degeneracy:

- Open condition: For any face  $\theta \subset \Delta$ , define  $f_{\theta}(x) = \sum_{m \in \theta \cap A} a_m X^m$ .
- Definition: f is  $\Delta$ -nondegenerate if for any face,

$$f_{\theta} = x_i \frac{d}{dx_i} f_{\theta} = 0 \tag{4}$$

has no solutions for all i in the torus over  $\overline{k}$ .

• Example:  $A = \{0, 1, ..., n\} \in \mathbb{Z}, f(x) = \sum a_i x^i$ .  $\Delta = [0, n], \text{ Faces: } [0, n], \{0\}, \{n\}, \text{ with } a_0 a_n \neq 0,$ and f(x) = f'(x) = 0 has no solutions. Toric Geometry:  $\mathbb{T}^d \subset \mathbb{P}_{\Delta}$ .

- $A = \{v_1, \dots, v_m\}$ . Assume  $\{v_i v_1\}$  generate M.
- Embed  $\mathbb{T}^d \subset \mathbb{P}^{|A|-1}$  via  $x \to (x^{v_1} : \cdots : x^{v_n})$ .
- $\overline{\mathbb{T}^d} = \mathbb{P}_{\Delta}, \, \mathbb{P}_{\Delta} = \operatorname{Proj} S_{\Delta}.$
- A cone  $C_{\Delta} \subset \tilde{M}_{\mathbb{R}}$ , generated by  $(1, v_1), \ldots (1, v_n)$ .
- The semigroup ring of  $C_{\Delta} \cap \tilde{M}$  under addition:  $K[C_{\Delta} \cap \tilde{M}] = S_{\Delta}$ .
- For our previous example:  $\{(1,0),\ldots,(1,n)\}.$

# Geometric Interpretation

- Take  $Z_f \subset \mathbb{T}^d$  defined by f = 0, compactification gives  $\overline{Z_f}$  and  $P_{\Delta}$ .
- $P_{\Delta} = \bigcup_{\theta \subset \Delta} \mathbb{T}_{\theta}^{\dim \theta}$ .
- Define  $Z_{f,\theta} = \mathbb{T}_{\theta}^{\dim \theta} \cap \overline{Z_f} \subset \mathbb{T}_{\theta}^{\dim \theta}$  defined by  $f_{\theta}$ . Hypersurfaces are smooth of codimension 1.

### Example

- Take  $\Delta = \text{Conv}(\{(0,0),(0,n),(n,0)\}).$
- $\mathbb{P}_{\Delta} \approx \mathbb{P}^2 \to \mathbb{P}^{n(n+1)/2-1}$ .
- $Z_f \to \overline{Z_f}$  curve of degree n.
- $Z_i = 0, i = 0, 1, 2$ , the line is  $\mathbb{P}^2$ .
- The curve  $\overline{Z_f} \cap \ell_i$  is transversal.

### Commutative Algebra

- $A \to F_0, \dots, F_d \in S^1_\Delta \subset S_\Delta \subset K[x_i^{\pm 1}], i = 1, \dots, d.$
- $F_0 = x_0 f(x), F_i = x_i \frac{\partial}{\partial x_i} F_0.$
- Theorem: f is  $\Delta$ -nondegenerate iff  $F_0, \ldots, F_d$  is a regular sequence in  $S_{\Delta}$ .
- i.e. multiplication by  $F_i$  is injective for all i in  $S_{\Delta}/\langle F_0, \ldots, F_{i-1} \rangle S_{\Delta}$ .
- $S_{\Delta}$  is a Cohen-Macaulay ring of Krull dimension d+1.
- For the triangle example,  $F_0 = xf(x)$ ,  $F_1 = x_0 x \frac{df}{dx}$ .

- Take N,  $\tilde{N} = \mathbb{Z} \oplus N$ .
- Embed  $M \to \tilde{M}$  by  $x^M \to \frac{dx^m}{x^m}$ .
- Identify  $M \otimes K = \Omega^1(\mathbb{T}^d)_{(1)}$ .
- $\operatorname{Lie}(\mathbb{T}^d) \approx N \otimes K$ ,  $\operatorname{Lie}(\mathbb{T}^{d+1}) = \tilde{N}$ .
- $S_{\Delta}(*,-)\otimes \Lambda^*\tilde{N}$ .

### Koszul Sequence

• We have a sequence

$$\cdots \to S_{\Delta}(-2) \to S_{\Delta}(-1) \to S_{\Delta}$$
, corresponding to  $\cdots \to S_{\Delta}(-2) \otimes \Lambda^2 \tilde{N} \to S_{\Delta}(-1) \otimes \Lambda^1 \tilde{N} \to S_{\Delta} \otimes \Lambda^0 \tilde{N}$ 

- Take a basis  $u_1, \ldots, u_{d+1}$  of  $\tilde{N}$ .
- $\Lambda^{s+1}\tilde{N}$ :  $d(u_{i_0} \wedge \cdots \wedge u_{i_s})$  is given by  $\sum_{j=0}^{s} (-1)^j \partial_{u_{i_j}} F_0 \wedge u_{i_1} \wedge \cdots \wedge u_{i_s} \wedge \cdots \wedge u_{i_r}.$
- Differential  $\partial_u F_0 = \sum_{m \in A} \langle (1, m), u \rangle_{a_m} x^{(1, m)}$ .
- Theorem: Koszul complex is acyclic except for degree i = 0.
- $H_i(C_0(H)) = S_{\Delta}/\langle F_0, \dots, F_{i-1} \rangle S_{\Delta} = S_f$ .

# Determinant of a Complex

- R is an integral domain,  $K = \operatorname{Frac}(R)$ .
- Take a complex of locally free R-modules  $\cdots \to C_k \to C_{k-1} \to \cdots \to C_1 \to C_0$  which is exact after tensoring with K.
- $\det(C_{\bullet}) \subset k$  is an R-module.
- For length 1:  $0 \to C_1 \to C_0 \to 0$ .
- $C_1 \otimes k$  and  $C_0 \otimes k$  are vector spaces of rank 1.
- det(C) = det(change of base matrix).